Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

# Applying Multivariate Extreme Value Theory to Environmental Data

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- "We anticipated as far as possible but one cannot forecast the unforeseeable" Xynthia's storm in France, 25 Feb 2010
- "It is impossible that the improbable never occurs"
   <u>Emil Julius Gumbel</u> (1891-1966)



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Oscar Wilde	e perspectiv	'e				

 "Man can believe the impossible, but man can never believe the improbable"
 Oscar Wilde (Intentions, 1891)

**Extreme events ?** ... a probabilistic concept linked to the **tail** behavior : low frequency of occurrence, large uncertainty and sometimes strong amplitude.



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An example						

Air pollutants (Leeds, UK, winter 94-98, daily max) NO vs. PM10 (left), SO2 vs. PM10 (center), and SO2 vs. NO (right) (Heffernan& Tawn 2004, Boldi & Davison, 2007)



Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
	estion					

What is the probability of observing data in the blue box ?



PM10

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#### A few facts about Extreme Value Theory

- An asymptotic probabilistic concept
- A statistical approach for extrapolation of quantiles
- A general framework with "weak" assumptions (ie no model for the full data set)
- Assessing uncertainties



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#### **Historical perspective**



Gumbel (1891-1966)

Weibull (1887-1979)

Fréchet (1878-1973)

- Emil Gumbel was born and trained as a statistician in Germany, forced to move to France and then the U.S. because of his pacifist and socialist views. He was a pioneer in the application of extreme value theory, particularly to climate and hydrology.
- Waloddi Weibull was a Swedish engineer famous for his pioneering work on reliability, providing a statistical treatment of fatigue, strength, and lifetime.
- Maurice Frechet was a French mathematician who made major contributions to pure mathematics as well as probability and statistics. He also collected empirical examples of heavy-tailed distributions.

Other important names : Fisher and Tippet (1928), Gnedenko (1943), etc

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Max-stabilit	y					

Let  $M_n = \max(X_1, \ldots, X_n)$  with  $X_i$  iid with distribution F.

Definition : F max-stable if

$$\mathbb{P}\left(\frac{M_n - b_n}{a_n} < x\right) = F^n(a_n x + b_n) = F(x)$$

#### **Examples**

Unit-Frèchet  $F(x) = \exp(-1/x)$  for x > 0. Then  $a_n = n \& b_n = 0$ 

**Gumbel**  $F(x) = \exp(-\exp(-x))$  for all real x. Then  $a_n = 1 \& b_n = \log n$ 

Weibull  $F(x) = \exp(-(-x)^{\alpha})$  for x < 0 (1 otherwise). Then  $a_n = n^{-1/\alpha}$ ,  $b_n = 0$ 

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**Maxima Distribution** 



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Generalized Extreme Value (GEV) distribution

$$\mathbb{P}\left(\frac{M_n - a_n}{b_n} < x\right) \sim \operatorname{GEV}(x) = \exp\left\{-\left[1 + \xi\left(\frac{x - \mu}{\sigma}\right)\right]_+^{-1/\xi}\right]$$



### From Bounded to Heavy tails



Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Intro sum	marv					

#### Modeling maxima : GEV

Stability for the max operator and  $X_0, X_1, \ldots X_n$  idd GEV

 $a \max(X_1,\ldots,X_n) + b = X$ 

# Note : Modeling excedances via Generalized Pareto Distribution If exceedances $(\mathbf{R} - u | \mathbf{R} > u)$ follows a GPD $(\sigma_u, \xi)$ then higher exceedances $(\mathbf{R} - v | \mathbf{R} > v)$ also follows GPD $(\sigma_u + (v - u)\xi, \xi)$

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### A few studies linking EVT with geophysical extremes

### Special issue of the journal Extremes, 2010

- Casson and Coles (1999) a Bayesian hierarchical model for wind speeds exceedances
- Stephenson and Tawn (2005) Bayesian modeling of sea-level and rainfall extremes
- Cooley et al. (2007) a Bayesian hierarchical GPD model that pooled precipitation data from different locations
- Chavez and Davison (2005) GAM for extreme temperatures (NAO)
- Wang et al. (2004) Wave heights with covariates
- Turkman et al. (2007), Spatial extremes of wildfire sizes
- Biodiversity and extreme temperatures, Sang and Gelfand, 2009
- Lichenometry, Jomelli et al., 2007
- Hydrology Katz et al.
- Downscaling <u>Vrac M., Kallache M., Rust H., Friedrichs P., etc</u>
- GCMs and RCMS analysis Smith R., Zwiers F., Maraun D., etc

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#### Limits of the univariate approach

#### Independence or conditional independence assumptions



Ribatet, Cooley and Davison (2010)

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### Why is Multivariate EVT needed?



How to perform spatial interpolation of extreme events ?

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

### Why is Multivariate EVT needed?

- Compute confidence intervals
- Calculating probabilities of joint extreme events

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
D		D' 1				
Rec	cipe for	Disaster	: The For	mula Th	at Killed	Wall
Str	eet					
By Felix	salmon 🖂 🛛 o:	2.23.09			1.1.1.1	
Р	$T[T_A < 1]$	., T <sub>B</sub> <1]	$= \Phi_2(\Phi)$	$-1(F_{A}(1)),$	$\Phi^{-1}(\mathbf{F}_{\mathbf{B}})$	$)\rangle,\gamma\rangle$
Her	e's what ki	lled your 4	01(k) David X	Li's Gaussian c	opula function as	first

published in 2000. Investors exploited it as a quick—and fatally flawed—way to assess risk. A shorter version appears on this month's cover of Wired.

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### A few geophysical applications of Multivariate EVT

- Sea surges & river flows (Gumbel conditional regression) Tawn et al., 2004
- Measuring the spatial dependence among rainfall maxima in Bourgogne (Max-stable processes) : Naveau & et al., (2009, Biometrika)
- Modeling multivariate dependence among pollutants (spectral EVT measures) : Cooley, Davis and Naveau (2009, JMVA)
- Spatial extremes, Bel, Bacro, Lantujenoul (2010)
- Extreme snow, Blanchet et al., 2010

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Mutivariat	e extreme	s				

# A few Approaches for modeling multivariate extremes

- Max-stable processes : Adapting asymptotic results for multivariate extremes Schlather & Tawn (2003), de Haan & Pereira (2005)
- Complete modeling : Auto-Regressive spatio-temporal heavy tailed processes, Davis and Mikosch (2007), AR-Gumbel Toulemonde et al. (2009)
- Copula approach : uniform marginals with extreme copulas, Genest et al., Charpentier
- Ribatet et al. (2010), Spatial R package for extremes
- Pseudo-likelihood inference Padoan, Ribatet and Sisson

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

Main question

How to model dependencies among maxima?

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## **Choice of marginals : unit-Fréchet**

$$F(x) = \exp(-1/x)$$
, for  $x > 0$ 



Fréchet (1878-1973)

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**Max-stable processes** 

## Max-stability in the univariate case with an unit-Fréchet margin

$$F^{t}(tx) = F(x)$$
, for  $F(x) = \exp(-1/x)$ 

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Max-stable processes

#### Max-stability in the univariate case with an unit-Fréchet margin

$$F^{t}(tx) = F(x)$$
, for  $F(x) = \exp(-1/x)$ 

Max-stability in the multivariate case with unit-Fréchet margins

$$F^t(tu,tv)=F(u,v)$$

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

A central question

F(u, v) = ?? such that  $F^{t}(tu, tv) = F(u, v)$ 

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

# A central question $F(u, v) = F^t(tu, tv)$

Suppose that  $F(u, v) = \exp(-V(u, v))$  and let  $(X_i, Y_i)$  iid with distribution F(u, v) and i = 1, ..., t

#### Link with counting processes

$$P(\max X_i \le tu, \max Y_i \le tv) = P(\forall i = 1, ..., t; X_i \le tu, Y_i \le tv),$$
  
=  $F^t(tu, tv),$   
=  $F(u, v),$   
=  $P($ Number of points in  $[u, \infty) \times [v, \infty)] = 0),$   
=  $\frac{(V(u, v))^0 \exp(-V(u, v))}{0!}$ 

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# A central question $F(u, v) = F^t(tu, tv)$

Suppose that  $F(u, v) = \exp(-V(u, v))$  and let  $(X_i, Y_i)$  iid with distribution F(u, v) and i = 1, ..., t

### Link with counting processes

$$\begin{split} P(\max X_i \leq tu, \max Y_i \leq tv) &= P(\forall i = 1, \dots, t; X_i \leq tu, Y_i \leq tv), \\ &= F^t(tu, tv), \\ &= F(u, v), \\ &= P(\text{Number of points in } [u, \infty) \times [v, \infty)] = 0), \\ &= \frac{(V(u, v))^0 \exp(-V(u, v))}{0!} \end{split}$$

#### Interpretation of V(u, v)

It can be viewed as the integrated Poisson intensity of the limit of

$$N_t(u,v) = \sum_{i=1}^t I[(X_i, Y_i) \notin [0, tu) \times [0, tv)]$$

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A central question  $F(u, v) = F^t(tu, tv)$ 

### Equivalence between F and V

 $F(u, v) = F^{t}(tu, tv)$  is equivalent to V(u, v) = tV(tu, tv)

### **Pseudo-polar coordinates**

The special case r = (u + v) and  $\omega_1 = \frac{u}{r}, \omega_2 = \frac{v}{r}$  (pseudo-polar coordinates) gives

$$F(u, v) = \exp\left(-\frac{1}{r} V(\omega_1, \omega_2)\right)$$

The Poisson intensity can be viewed as a product of two independent components : a radius (strength) and an angular (direction)

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### **Polar coordinates**

**2D**  r = (u + v) and  $\omega_1 = \frac{u}{r}, \omega_2 = \frac{v}{r}$ 



**3D**  

$$r = (u + v + w),$$
  
 $\omega_1 = \frac{u}{r}, \omega_2 = \frac{v}{r}, \omega_3 = \frac{w}{r}$ 



Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
2D Polar co	ordinatos					

### **2D** : **INDEPENDENT CASE** r = (u + v) and $\omega_1 = \frac{u}{r}, \omega_2 = \frac{v}{r}$

### **2D : COMPLETE DEPENDENCE** r = (u + v) and $\omega_1 = \frac{u}{r}, \omega_2 = \frac{v}{r}$





#### Examples : fitting multivariate maxima

Air pollutants (Leeds, UK, winter 94-98, daily max) NO vs. PM10 (left), SO2 vs. PM10 (center), and SO2 vs. NO (right) (Heffernan& Tawn 2004, Boldi & Davison, 2007)



#### Our strategy

- 1 Assume observations arise from a max-stable process
- 2 Find and fit a flexible parametric model for the spectral density
- 3 Two desiderata : (A) interpretable parameters & (B) going beyond the bivariate case

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Multivariate Max-Stable Distributions (de Haan, Resnick)

If  $\mathbf{Z} = (Z(\mathbf{x}_1), \dots, Z(\mathbf{x}_p))^T$  has a multivariate max-stable distribution with unit Fréchet margins ( $\mathbb{P}(Z(\mathbf{x}_i) \leq z) = \exp(-z^{-1})$ ) then :

$$G(\boldsymbol{z}) = \mathbb{P}(\boldsymbol{Z} \leq \boldsymbol{z}) = \exp[-V(\boldsymbol{z})], \text{ where}$$

$$V(\boldsymbol{z}) = \rho \int_{S_{\rho}} \max_{i} \left( \frac{w_{i}}{z_{i}} \right) dH(\boldsymbol{w}),$$

*H* is a positive measure on  $S_p$ , s.t.

$$\int_{\mathcal{S}_p} w_i dH(\boldsymbol{w}) = 1/p,$$

and  $S_{\rho} = \{ \boldsymbol{w} \in \mathbb{R}^{\rho}_+ | w_1 + \ldots + w_{\rho} = 1 \}.$ 

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Models	for Multivaria	te MSD's				
	Exponent me	easure functior (( <i>z</i> )	1	Spectr h		
	<ul> <li>Logistic</li> <li>Asymmetric I (Tawn, 88)</li> <li>Negative Log (Joe, 90)</li> </ul>	Logistic jistic		<ul> <li>Dirichlet (Coles &amp; Tawn, 91)</li> <li>Dirichlet mixture (Boldi &amp; Davison, 2006)</li> <li>Pairwise Beta (Cooley, Davis and Naveau)</li> </ul>		
+	- Can obtain G - Overparame	G( <i>z</i> ) trized ?	+	- More flexibili	ty ?	

- Less flexible?

Cannot directly get G(z)

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

Dificnlet model (Coles, Tawn, 1991) 
$$\int_{S_p} w_i dH(\mathbf{w}) = 1/p$$

$$h(\boldsymbol{w};\boldsymbol{\theta}) = \frac{1}{p}(\boldsymbol{m}\cdot\boldsymbol{w})^{-(p+1)}\prod_{j=1}^{p}m_{j}h^{*}\left(\frac{m_{1}w_{1}}{\boldsymbol{m}\cdot\boldsymbol{w}},\ldots,\frac{m_{p}w_{p}}{\boldsymbol{m}\cdot\boldsymbol{w}};\boldsymbol{\theta}\right)$$

A special case : Dirichlet model

$$h^*(\boldsymbol{w};\boldsymbol{\alpha}) = \frac{\Gamma(\boldsymbol{\alpha}\cdot\boldsymbol{1})}{\prod_{j=1}^p \Gamma(\alpha_j)} \prod_{j=1}^p w_j^{\alpha_j-1}, \ \alpha_j > 0, j = 1, \dots, p.$$

$$h(\boldsymbol{w};\alpha) = \frac{1}{p} \prod_{j=1}^{p} \frac{\alpha_j}{\Gamma(\alpha_j)} \frac{\Gamma(\boldsymbol{\alpha} \cdot \boldsymbol{1} + 1)}{(\boldsymbol{\alpha} \cdot \boldsymbol{w})^{p+1}} \prod_{j=1}^{p} \left(\frac{\alpha_j w_j}{\boldsymbol{\alpha} \cdot \boldsymbol{w}}\right)^{\alpha_j - 1}$$

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**Our Pairwise Beta Model** 

$$h_{\rho}(\boldsymbol{w}; \alpha, \beta) = K_{\rho}(\alpha) \sum_{i \neq j} h_{i,j}(\boldsymbol{w}_i, \boldsymbol{w}_j; \alpha, \beta_{i,j}), \text{ where}$$

$$h_{i,j}(\boldsymbol{w}_i, \boldsymbol{w}_j; \alpha, \beta_{i,j}) = (\boldsymbol{w}_i + \boldsymbol{w}_j)^{(\rho-1)(\alpha-1)} (1 - (\boldsymbol{w}_i + \boldsymbol{w}_j))^{\alpha-1} \times \frac{\Gamma(2\beta_{i,j})}{(\Gamma(\beta_{i,j}))^2} \left(\frac{\boldsymbol{w}_i}{\boldsymbol{w}_i + \boldsymbol{w}_j}\right)^{\beta_{i,j}-1} \left(\frac{\boldsymbol{w}_j}{\boldsymbol{w}_i + \boldsymbol{w}_j}\right)^{\beta_{i,j}-1}$$

Advantages :

- no adjustment necessary to get center of mass condition  $\int w_j dH(\mathbf{w}) = 1/p$
- **parameters** have some interpretation :  $\alpha$  controls overall dependence,  $\beta_{i,j}$ 's control pairwise dependence
- largely specified by pairwise parameters
- Middle ground between Coles & Tawn (1991) and Boldi & Davison (2007)

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#### **Pairwise Beta Models**









Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Fitting the s	pectral der	nsity model				

Beirlant at al., (2004), Coles & Tawn (2004), Boldi & Davison (2007)

(a) have common marginals with unit tail index

(b) transform into polar coordinates and select exceedances above  $t_0$  (c) maximize the likelihood

$$L(\boldsymbol{\theta}; (r_{(i)}, \boldsymbol{w}_{(i)}), i = 1, \dots, N_{t_0}) \approx \exp(-\nu(A)) \prod_{i=1}^{N_{t_0}} d\nu(r_{(i)}, \boldsymbol{w}_{(i)}) = \exp(-t_0^{-1}) \prod_{i=1}^{N_{t_0}} r_{(i)}^{-2} h(\boldsymbol{w}_{(i)}, \boldsymbol{\theta}),$$

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

#### Air pollutants example





Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Air polluto	ato oxomo	lo				





100 largest observations. corners= PM10 (lower right), NO (upper left), SO2 (lower left)

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#### Prediction : Approximating the conditional density?



If  $V(\mathbf{z})$  is known and differentiable, then joint density can be obtained exactly. However, we are modeling  $h(\mathbf{w})$ . Assume  $Z_1, Z_2$  are observed and  $Z_0$  is unobserved. Any predictor  $Z_0^*$  will yield a point  $\mathbf{Z}^* = (Z_0^*, Z_1, Z_2)$  which can be mapped back to  $S_p$  as  $\frac{\mathbf{Z}^*}{\|\mathbf{Z}^*\|_1}$ .

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Approximating the conditional density?

If  $V(\mathbf{z}) = \mu\{(0, \mathbf{z}]^c\}$  is small (i.e. the radius is large), then

$$G(\mathbf{z}) = \exp(-V(\mathbf{z})) \approx 1 - V(\mathbf{z}).$$

Using Coles and Tawn (91) result to estimate the density at z :

$$g(\boldsymbol{z}) \approx rac{\partial}{\partial z_1, \ldots, \partial z_p} [1 - V(\boldsymbol{z})] = rac{1}{||\boldsymbol{z}||^{-(p+1)}} h\left(rac{\boldsymbol{z}}{||\boldsymbol{z}||}\right)$$

So conditional density can be approximated by

$$g_{Z_{p}|Z_{1},...Z_{p-1}}(Z_{p}|Z_{1},...,Z_{p-1}) \approx \frac{\frac{1}{||\boldsymbol{Z}||^{-(p+1)}}h\left(\frac{\boldsymbol{Z}}{||\boldsymbol{Z}||}\right)}{\int_{0}^{\infty}\frac{1}{||\boldsymbol{Z}^{*}||^{-(p+1)}}h\left(\frac{\boldsymbol{Z}^{*}}{||\boldsymbol{Z}^{*}||}\right)d\zeta}$$

where  $z^* = (z_1, ..., z_{p-1}, \zeta)$ .



Approximating the conditional density?

Three realizations from a trivariate symmetric logistic distribution. True conditional density (solid line) and approximated conditional density (dotted line)



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#### Summary of our spectral approach

- "Simple" and flexible spectral density with interpretable parameters
- Can be used for prediction or interpolation purposes
- Can be generalized (Ballani, Schlather, 2010)
- Can be extended to the asymptotic independent case (Qin, Smith, Ren, 2008)

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion
Take home	messages	5				

- Multivariate EVT may help characterizing extremes dependencies in space and time
- Physical knowledge should be integrated into the statistical analysis
- Computational issues can be arisen quickly
- Modeling trade off between parametric and non-parametric approaches
- Asymptotic independence can be an issue
- Extremes here means very rare

### Two advertisements

- Extreme Value Analysis (EVA, Lyon June 27th to July 1st, 2011)
- Environmental Risk and Extreme Events, Workshop, Ascona, July 10-15 2011

Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

# An example with $\alpha = 1$ , $\beta = (2, 4, 15)$





# An example with $\alpha = 1$ , $\beta = (2, 4, 15)$ (... = asymptotic mle) 200 real \* 1000



Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

#### A main random variable of interest : precipitation

- 1 Relevant parameter in meteorology and climatology
- 2 Highly stochastic nature compared to other meteorological parameters



Motivation	Basics	Applic	Max-stable	Spectral	Prediction	Conclusion

### Estimating the GPD parameters estimates $(\hat{\sigma}_u, \hat{\xi})$

- Maximum likelihood estimation
- Methods of moments type (PWM and GPWM, Ribereau et al., 2010)
- Exhaustive tail-index approaches
- MCMC techniques

### Taking advantages of the stability property

Mean Excess function

$$\mathbb{E}(\mathbf{R}-u|\mathbf{R}>u)=\frac{\sigma_u+u\xi}{1-\xi}$$

- the scale parameter varies linearly in the threshold *u*
- the shape parameter  $\xi$  is fixed wrt the threshold u