

Modelling extreme values of processes observed at irregular time step

Extreme Environmental Events

Nicolas Raillard

Université de Bretagne Occidentale
IFREMER
Brest, France

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Introduction

Objectives

- Spatio-temporal peaks-over-thresholds
- Application: Satellite data, in-situ observations, hindcast data...

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Univariate probabilistic theory

- Limit theorems for $\frac{\sum_{i=1}^n X_i - b_n}{a_n}$: CLT, α -stable distributions...
- For the tails: $S_n \leftrightarrow M_n = \max_{i=1, \dots, n} X_i$
- If $F^n(a_n x + b_n) = \mathbb{P}\left\{\frac{M_n - b_n}{a_n} \leq x\right\} \rightarrow G(x)$, then G is a max-stable distribution: $G^n(\alpha_n x + \beta_n) = G(x)$
- Fisher-Tippett (1928), Gnedenko (1943):

$$G(x; \mu, \sigma, \xi) = \exp\left[-\left(1 + \xi \frac{x - \mu}{\sigma}\right)_+^{-1/\xi}\right] \in \text{GEV}(\mu, \sigma, \xi)$$
- Example:
 - Type Weibull: $\xi < 0$ (including Rayleigh...)
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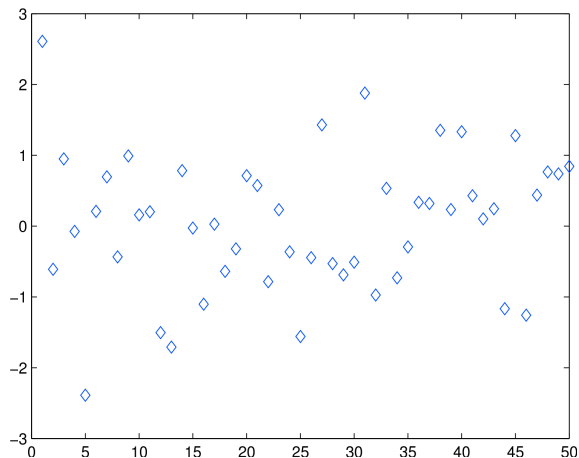
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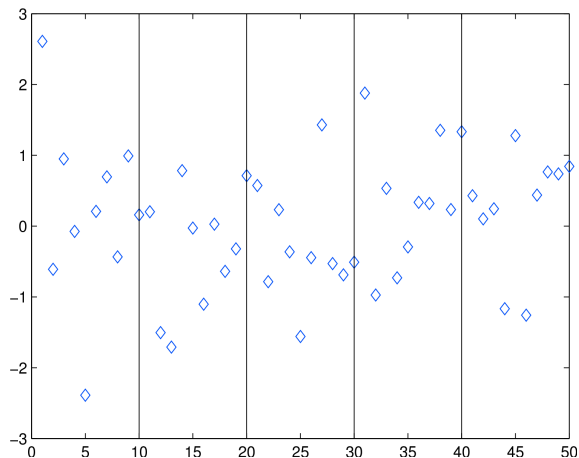
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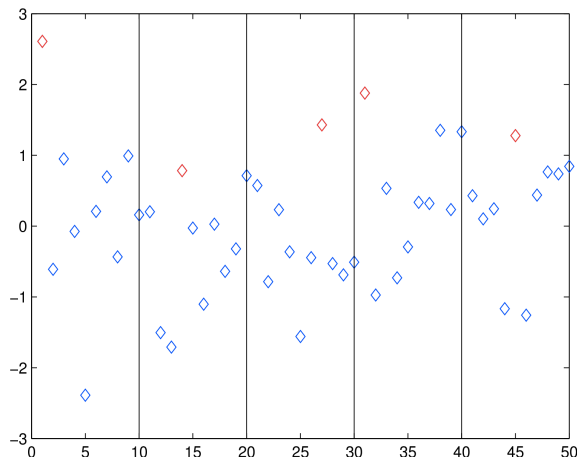
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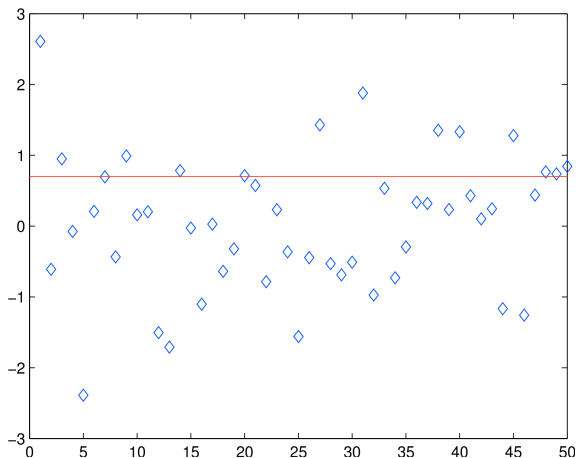
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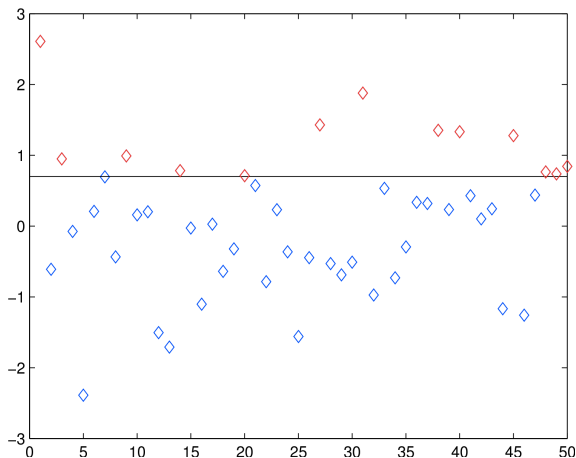
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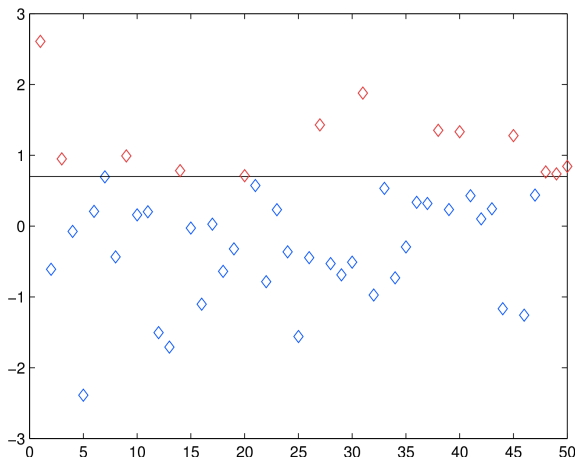
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Solutions to time-dependence in POT

2 approaches:

① **Declustering** (Coles, 2001)

- Identify Clusters
- Fit the marginal distribution to maximum excess within each cluster
- Estimate the extremal index to **correct** the return period

② **Modelling all exceedances** of the threshold (Smith, 1997; Ribatet 2009)

- Advantages: no need to define a cluster; all excess are kept
- Drawbacks: Need for a dependence modelling; less usual
- Usually: Markov Chain model for consecutive observations: need for constant time-step; strong assumption

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Modelling dependence

Smith's max-stable process

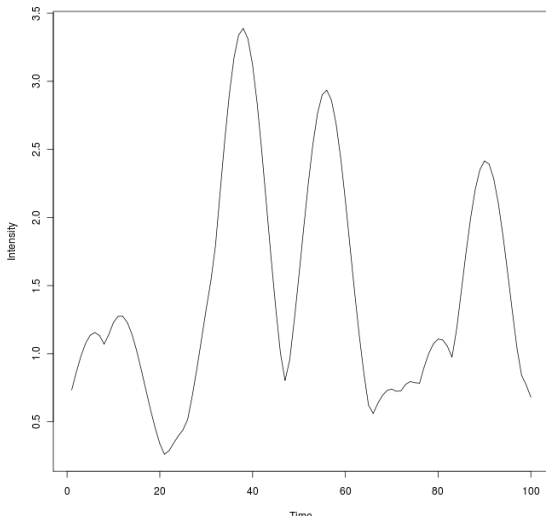
Extension of **max-stable concept for processes** (de Haan, 1986: Smith, 1990), with unit Fréchet marginal distributions.

$$\forall t \in \mathbb{R}, Z(t) = \max_{i=1, \dots} \{\lambda_i f(t, Y_i)\}$$

with: $f(s, t) = \varphi(s - t)$, φ p.d.f of $\mathcal{N}(0, 1)$, (λ_i, Y_i) points of a Poisson process with intensity $\lambda^{-2} d\lambda/ds$

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⇒ use of a **composite likelihood method** (Varin, 2008):

$$CL(z_{t_1}, \dots, z_{t_n}; \theta) = \prod_{i=1}^{n-K} \prod_{j=i+1}^{i+K} p(z_{t_i}, z_{t_j}; \theta)$$

Application to peaks over a high threshold

Model

Model for excess

- Observations $\{X_{t_i}\}_{i=1,\dots,n}$
- If $X_{t_i} > u$, $X_{t_i} = \tilde{X}_{t_i}$ where \tilde{X}_t is a max-stable process:
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 - $\Rightarrow Z_t = -1/\log G(X_t; \mu, \sigma, \xi) \sim \text{Fréchet}(1)$
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- Under study: consistency of the uncensored one-lagged CL estimator (i.e. with $K = 1$)
- Perspectives:
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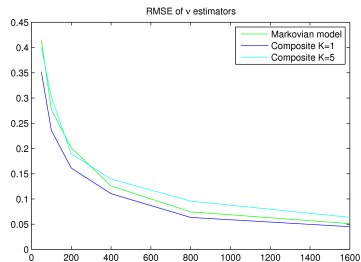
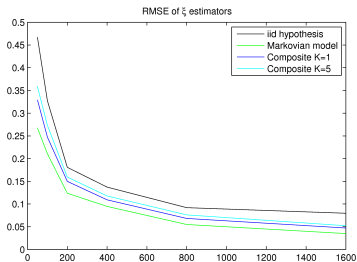
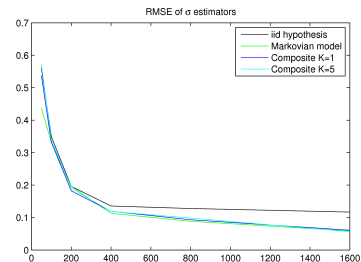
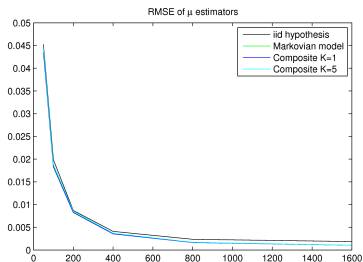


Figure: RMSE of the different estimators

Robustness

Question: Is this model able to catch extremal properties of usual time series models?

- 10 years return level: level which is exceeded on average once every 10 years
- Frequency and length of extremal events
- Sum of the values above the threshold

Robustness

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Method:

- Simulation of $X_t = \varphi X_{t-1} + \mathcal{N}(0, \sqrt{1 - \varphi^2})$ of length 100 years (with 1 obs./day)
- Fitting the model
- 100 times:
 - Simulation of the fitted model over 10 years, and computation of the statistics
 - Simulation of the $AR(1)$ over 10 years, and computation of the statistics

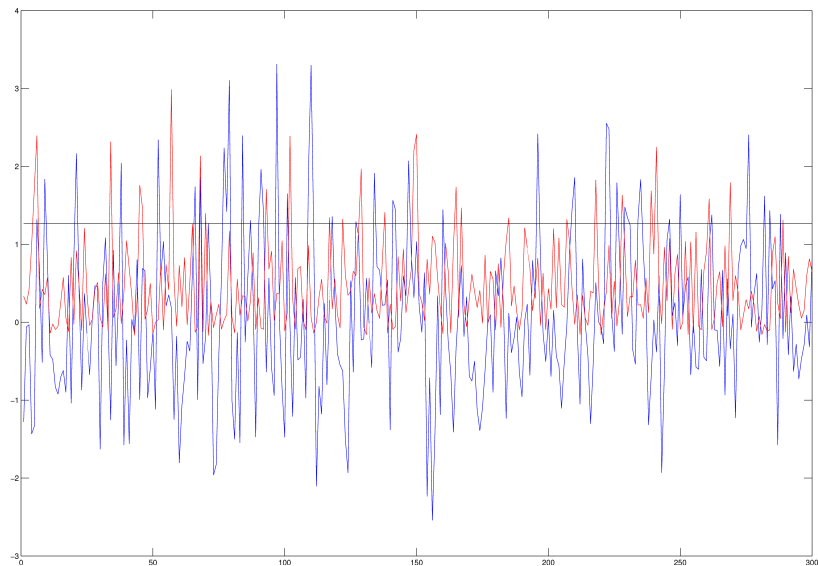


Figure: Example of simulated data (Blue) vs. fitted model (Red) and selected threshold (Black)

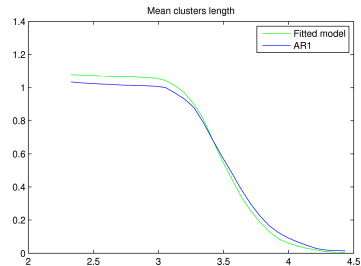
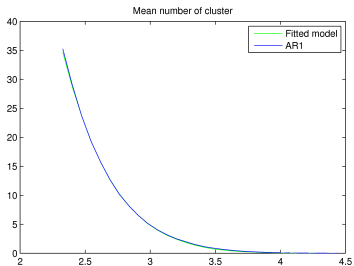
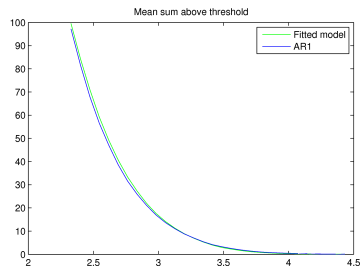
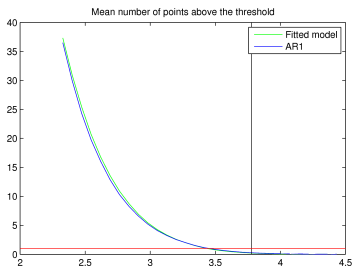


Figure: Statistics computed for an AR(1) process with $\varphi = 0.2$

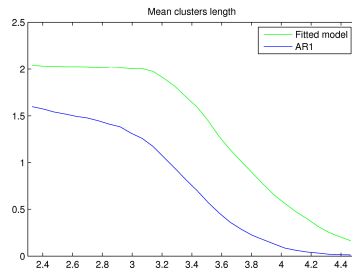
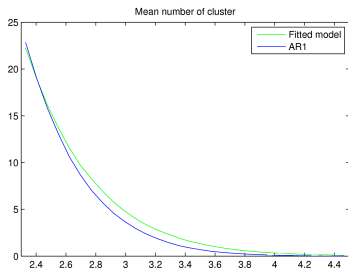
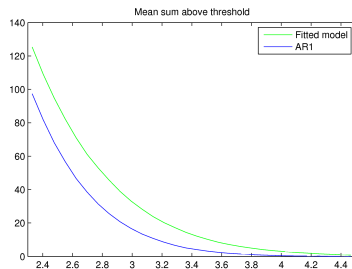
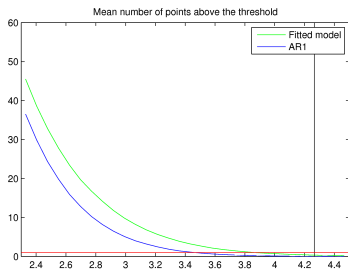


Figure: Statistics computed for an AR(1) process with $\varphi = 0.8$

Contents

- 1 Statistical modelling
 - Univariate extreme values modelling
 - Modelling dependence
- 2 Statistical inference
 - Theoretical results
 - Simulation results
- 3 Conclusion

Conclusion

... and prospects

- We obtained a flexible model that can account for irregular data spacing and missing values
- Ongoing: application to satellite and in-situ data
- Perspectives:
 - Theoretical results :asymptotic normality, choice of K , influence of censoring...
 - Extensions: space-time modelling...



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